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G20M

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1 Introduction

1.1 Company Introduction

Guangzhou Geosurv Information Technology Co., LTD is a company professional in surveying and mapping industry. Advanced and high-quality products are our top priority. We try our best to offer prompt and good service to all our customers. Rich experience and abundant knowledge in this field guarantee that every decision we made is on the basis of scientific test. We strive to provide great products and service with reasonable price and believe it's the key to have more clients and gain more cooperation.

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1.2 Outstanding Features of GINTEC G20M

Purchasing the right tools for a professional job is essential in today's competitive business environment. As the latest GNSS receiver, G20M distinguishes itself from other GNSS products. It is more compact and lightweight but integrating more advanced technology. Even still equipped with magnesium alloy fuselage, the dimension is only 100x100x61.5mm and the weight is just 555g. Many revolutionary technology in G20M makes your survey work more quickly and efficiently. Some innovation features can be summarized as below:

Small and Light Design

With only 580g magnesium alloy design, G20M will be a powerful productive rover for surveyors in topographic and mapping, infrastructure and construction.

Full Constellation Tracking

G20M can track full constellation GNSS satellites: GPS, Glonass, Galileo and BeiDo u. It maximizes the tracking to observe all visible and available GNSS satellite signals. With the aid of UGypsophila RTK processing tech, G20M uses and locks more satellites, thereby performing better for realtime reliable accuracy.

IMU Tilt Survey Compatible with SurPad

Integrated with new calibration-free IMU module and based on 4th generation pole-tilt compensation tech, G20M enables points to be measured or staked out even if surveyors tilt the pole while walking. Surveyors could pay more attention to their job at hand and complete work faster.

Fast-Charge Tech

G20M provides type-C charging interface and supports multiple fast charging protocols.

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Surveyors can charge G20M using portable phone battery anytime and anywhere.

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Long Life Battery

With a built-in large- capacity lithium battery, G20M can last all day without stopping. Smart power button design can indicate battery level even in shutdown status.

Smart WEB UI Control

To provide a friendlier experience for first-timers and experienced users, we provide users with 2 kinds of WEB UI: Smart and Professional.

All of these innovations will increase your productivity and taking your performance to a new level.

2 General Information

2.1 Outlook of G20M



C: Reset button D: USB port E: SIM card slot

The indicator status: light or blink. It represents different status of the RTK equipment:

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TIM	4	Bluetooth Indicator	Light on when device has been connected via
	*		Bluetooth.
	Ø	Satellites Indicator	Blink when normally receive satellites signals.
	(T)	Datalink Indicator	Blink when differential data is received.
	Ē	Power Indicator	Red light on when device is charging; Green light on
	6	VICL	when fully charging. Red light blinks when device is
			in low battery

2.2 Basic Operation

2.2.1 Turn on/off

Turn on

This is the very first step to use G20M. When the receiver has power, keep pressing power button for 3 seconds, then you will see the power button light up and hear beep.

Turn off

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Keep pressing power button for 3 seconds, then you will hear beep voice and the device will be turned off.

If the device crash down, press Reset button to force it to turn off.

2.2.2 Charging

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Red light on when device is charging. Green light on when fully charging. G20M supports MTK PE1.1/2.0 and PD protocol fast charging. Choose the fastcharging adapter to charge it can greatly shorten charging time.

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GNTEC GN 3 Equipment Packing List

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4 Setting Up

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4.1 Setting Up Base Station

4.1.1 Choose a suitable place

A suitable place is essential for base station to better receive the satellites and transmit the UHF signals. A suitable position should comply with following conditions:

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(1) Choose a wide-open area in order to easy and better receive signal of satellites. Besides, make sure there is no covering like roof or heavy foliage.

(2) A higher place is better for transmitting the UHF signals. If rover is far away from base, then the enhanced antenna should be raised by tripod.

(3) Make sure there is no large area of water or objects intensely interfering the satellite signal.

(4) Check carefully that there are no high-power radio emission objects surrounded. And make sure there is no power lines around. Need keep at least 200m far from these objects.

4.1.2 Set up instrument

Mount the instrument to the tripod. Level and center the instrument precisely to ensure the best performance. You can set up base on random point or on given point. If you set base on random point, you just choose a position and level the instrument. If you set base on given point, you can follow below steps:

(1) Leveling and Centering the instrument

a. Setting up tripod

First, extend the extension legs to suitable length, make the tripod head parallel to the ground and tighten the screws.

b. Make the center of the tripod and the occupied point approximately on the same plumb line.

c. Step on the tripod to make sure if it is well stationed on the ground.

(2) Attaching the instrument on the tripodPlace the instrument carefully on the tripod head and slid the instrument by loosening the tripod screw.

(3) Roughly leveling the instrument by using the circular vial

a. Turn the leveling screw A and B to move the bubble in the circular vial as below Figure 4-1 shown, in which case the bubble is located on a line perpendicular to a line

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Figure 4.

b. Turn the leveling screw C to move the bubble to the center of the circular vial.



Figure 4-2

(4) Precisely leveling by using the plate vial

a. Rotate the instrument horizontally by loosening the horizontal clamp screw and place the plate vial parallel to the line connecting leveling screw A and B, and then bring the bubble to the center of the plate vial by turning the leveling screws A and B. GINI

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Figure 4-3

b. Rotate the instrument 90^0 around its vertical axis and turn the remaining leveling screw or leveling C to center the bubble once more.

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c. Repeat the above a & b steps for each 90^0 rotations of the instrument and check whether the bubble is correctly centered in all directions.

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4.1.3 Measure antenna height

The antenna height must be measured when we use G20M to collect static data or use it as base station. It's the "a" show in below Figure 4-5, the height from ground measured point to phase center, only get this height can we know coordinate of the ground measured point. There are 3 measuring methods to get the antenna height:

(1) Slant height

Measure the distance from the ground measured point to the middle of mainframe scale mark. It's the "d" shown in Figure 4-5.

(2) Pole height

Measure the distance from bottom of device to ground directly. It's the vertical height "b" shown in Figure 4-5.

(3) Measuring plate

Measure the distance ground measured point to the upper edge of plate. It's the "c" shown in Figure 4-5.

Choose either one measuring method from above. Use measure tape measure the height you choose. Input the height in software. Then you can get the height from ground to phase center. The formula is as below: INITE

altimetry piece

Ground

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a=b+L1

(<u>*</u>@*

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 t_0

heiaht

slant

slant height

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Vertical height

Figure 4-5 (Measure Antenna Height)

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Height to phase center

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4.1.4 Transmit signal through network

You can also use network (G20M has 4G module supports 4G network) to transmit signal. Insert SIM card into the receiver. And select network datalink via controller or WEB UI function. GINTEC

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4.2 Setting Up Rover Station

Rover station can receive data through different datalink methods--internal radio, rover network and controller network.

4.2.1 Connect controller with rover

Attached the controller bracket to the pole. If use internal 4G, you need to insert the SIM card in controller. If use internal radio, then fix UHF antenna. You can connect the controller with rover through Bluetooth as you prefer.

Via Bluetooth

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Use controller to search the Bluetooth signal of G20M, once found, the Serial NO. of G20M will show on controller, then select it to finish connect.

4.2.2 Rover network mode

Insert SIM card on rover, then select network mode on controller or via WEB UI function. Input the CORS account and password, set APN and upload GGA.

4.2.3 Rover controller network

This method means the SIM card is inserted in controller. The controller gets the correction data and send to device via Bluetooth. It's less stable compare with device network. JULIE

4.2.4 Download backup data

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Once finish surveying, you can download the backup data via WEB UI as shown in Figure 4-8. The backup data format is ". dev" GINTER

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	БI	JTEC	БIN	TEC		
	Simple UI	File				
	Status					
	Command	Root/ 20201209/ ch02/				
	Mode Contig					
	Others Config		Name	Size	Operation	
	File		Z30476867008303-02-20201209-070910.dev	547.34kB	Download	
	Firmware		Z30476867008303-02-20201209-072143.dev	56.89kB	Download	
			Z30476867008303-02-20201209-082013.dev	1.26MB	Download	
GIN	EL		Figure 4-8			

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4.3 Static Surveying

Static surveying requests at least 2 receivers put on 2 points on a baseline. Keep these receivers in the same position and track at least 4 satellites then get relative distance of these 2 points. Static surveying provides the highest accuracy achievable and requires the longest observation times, from less than an hour to five hours or longer.

The static surveying function in G20M including outdoor surveying and indoor data post processing. GINTEC

4.3.1 Baseline network design

(1) Synchronous pattern

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As we know, static surveying uses at least two or more than two receivers track same satellites during same period. And then we can get data of these points. The pattern that formed by these points called synchronizing pattern. If use three or more than three receivers, the pattern formed by these points called synchronizing pattern cycle. As show in Figure 4-9.



If there are too many points in one baseline network, you should connect these synchronous cycles together and form the asynchronous pattern.

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Asynchronous pattern can be connected via three ways as shown in Figure 4-10:

(a) Point connecting. Point connecting network is defined as a figure by connecting two adjacent shapes by only one common point. The advantage of this type is high efficiency, fast extending. But it cannot confirm the high precision surveying. Therefore, it is not recommended in precise working.

(b) Side connecting. Side connecting network is defined as a figure by connecting two adjacent shapes by their same side. It is widely used in the surveying field due to its high precision.

(c) Point and side connecting. Because every type of network has its own advantage and disadvantage, we can combine these types to achieve higher efficiency but lower investment in time. Mixed connecting network is common in surveying work.



Figure 4-10 (asynchronous pattern)

4.3.2 Outdoor surveying

(1) Choose suitable points

Suitable points are essential to make sure whole surveying work goes smoothly and efficiently. The points should be fixed only after you well analyze and collect full information of the surveying area. Choose these points best suits your accuracy and surveying purpose. When choose the point in static surveying, you should pay attention to below:

a. The points should comply with your surveying purpose.

b. The points should also be easy-to-use for other surveying methods.

c. Convenient transportation. So, it's easy for you to set up device.

d. Away from high power radio emission objects, make sure no magnetic field influence nearby.

e. Away from large water area or mirror building, reduce the multi-path interface.

f. Good ground foundation, so the point can be saved enduringly.

g. Make marks after choose the points, including its position info and sketch of its surroundings.

(2) Setting up devices

After choose the points, you set up the device on these points. Power on the device, then you can set "Static Mode" via controller software or WEB UI. As shown in below

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GINTED GINTEC GINTEC FC Figure 4-11. Mode Config Working Mode Mode Config Mode: Static Mode ~ GINT Elev Cutoff: 5 PDOP Threshold: 3.0 JTEC Station Name Z30476867008303 Height Type: Buttom ~ 0 Antenna Height: Apply GINT Copyright 2019 - 2020 GINTEC GINTE NTEC Static mode settings **Options Settings** GINTEC Z30486867007923 Point name PDOP limit 3.0 🔾 GINTEC Cut-off angle 5 > Collection Interval 1s > Antenna Parameters GINT 13 Antenna Measured Height Antenna **IEC** Vertical height >Measurement Type GIN 1.059 Antenna Height ITEC

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Figure 4-11

Apply

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You can define the point name and set interval frequency and input the antenna height and others. Once working, you can observe the satellite signal status and record the satellite data in device or in controller.

4.3.3 Download data

Connect G20M via WEB UI for data downloading. File name given should comply with the notes of outdoor surveying made by yourself. Data file name includes station name and days of the year. It is easy for you to distinguish.

	1Z30486867007923		[Advance UI] English	×
Simple UI	File			
Status				
	Root/ 20201215/ ch01/			
	Name	Size	Operation	
File	Z30486867007923350a.dev	2.60MB	Download	
5 WED	UI Control			

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5 WEB UI Control

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5.1 Connect and register WEB UI

G20M can be a Hotspot. You can connect it with phone, controller, PC or other devices through its Wi-Fi. The default Wi-Fi name is device S/N number, no password needed. After connecting the Wi-Fi, input IP"192.168.10.1" into your web browser to turn it on.

← C ☆ ♥ http://192.168.10.1/#

Then you will enter the WEB UI interface, as shown in Figure 5-1.

← → C ▲ 不安全 19	92.168.10.1						
	Z30476867008	303				[Advance UI] English -	
Simple UI	Status						
Status							
Command	1-6-						
Mode Config	into	CNI:	720476967009202				
Others Config		514.	1.55 2012 202				
File		Firmware:	1.55.2012.293				
Firmware	Mode						
		Working Mode:	Rover Mode				
		Diff Chain:	Inside Network Chain				
	GNSS						
		Local Time:	2020-12-09 16:38:43.000				
		Quality:	1				
		Satellite Used:	28				
		Diff:	0				
		Latitude:		23.16502803 °			
		Longitude:		113.43036496 °	HRMSE:	2.222 m	
		Height:		63.561 m	VRMSE:	4.301 m	
 1 C C C C C C C C C C C C C C C C C C C		HDOP:	0.62		PDOP:	1.33	

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The WEB UI includes Status, Command, Mode Config, Others Config, File and Firmware.

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5.2 Status

In "Status", you can see current work status of receiver and some basic information. Including Device Info, Mode and GNSS Info. (As shown in Figure 5-1)

5.3 Command

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In "Command" you can reboot/shutdown G20M, reset config (Reset factory settings), clean storage and Register code.

	clean storage and F	legister code.	
	Simple UI	Command	
	Status		
	Command	Suctam	
	Mode Config	System	
	Others Config	Reboot Shutdown	
	File		
	Firmware	Config and Data	
TEL		Reset Config Clean Storage	
N C		Register Code	
		negister coue	
		Register	
		sn=Z30486867010338 date=2021-02-22	
5			
	Copyright 2019 - 2020 GINTEC		
		Figure 5-2	
Tec	5.4 Mode Con	fig	
	In "Mode Config"	you can set working mode.	
	In "Working Mode"	", you can select different work modes: Rover Mode, F	Base Mode or
	Static Mode. In dif	ferent mode, you can define different configuration.	
			TCC
		CIVITE O	
	TC		
		CINITE	

GINTER GINTEC GINTEC F Base Mode Mode Config Simple UI Working Mode Mode Config Mode: Base Mode ~ GINT Elev Cutoff: 5 Station ID: 0 PDOP Threshold: 0 JTEC Diff Type: RTCM32 Base Mode: Auto ~ Chain Diff Chain: Mobile Phone Network Chair 🗸 GIN Copyright 2019 - 2020 GINTEC 17 Rover Mode Mode Config Simple UI Working Mode F Mode Config Mode: Rover Mode ~ Elev Cutoff: 5 -Chain GINT Diff Chain: Mobile Phone Network Chair 🗸 Apply ITEC GINTEC GINTEC GINTEC GINTE GINTEC GINITED

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	GINITE	E GINI		y = -
FL		Static Mode		
	Simple UI	Iode Config		
	Status			
	Command	Working Mode		
	Others Config	Mada Commence		
	File	Mode: Static Mode	~	
GIN I	Firmware	Elev Cutoff: 5		
		PDOP Threshold: 3.0		
		Station Name Z30486867010338	8	
				ITFL
		Height Type: Buttom	~	
		Antenna Height: 0		
NTEC	In "Other Config", you Simple UI	can config satellite systems and WIF	FI.	_
	Command	Satellite System		
	Mode Config Others Config	BDS: 🗸 Enable		'–Г
	File	GALILEO: 🗸 Enable		
	Filliwale	GPS: VEnable		
Ы				
		WiFi		T
		WiFi: AP	~	GINT
		SSID: Z30486867010338		
Ter		PSK:	Empty or Length not less than 8	
IEL				
	Copyright 2019 - 2020		Apply	
	GINTEC			
		Figure 5-4	GIVI F	
	5.6 File	GINITEL		
	In "File" you can del	te or download data files. If you was	nt to download static data	

E In "File", you can delete or download data files. If you want to download static data, choose the correct file and find static file in ch01 then download.

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-	БIЛ	JTEC	БINT	EC	6	
	Simple UI	File				
	Command	Post/				
	Mode Config	NUOY				
	Others Config		Name	Size	Operation	
	File		20201202/		Delete	
	Simple III	File				
	Status	1110				
	Command					
	Mode Config	Root/ 20201202/ ch02/				
	Others Config		Name	Size	Operation	
יעוכו	File		Z30486867010338-02-20201202-094537.dev	4.43kB	Download	
			Figure 5-5			
				_	GIN	JTE
	5.7 Firm	ware	GINIE			

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In "Firmware", you can find the current G20M Version installed and upgrade firmware.

	Simple UI	Firmware			
	Status				
	Command				
	Mode Config	version			
	Others Config	System	1.15.2012.19		
	File	Linux Version	3.18.44 Tue Dec 1 11:50:17 CST 2020		
	Firmware	GNSS Firmware	R3.00Build21759		
		IM19 Firmware	B1.2_A2.9_b9f4f9a11bc9da		
		Firmware	1.49.2011.277		
-L				Upgrade	
		Fi	gure 5-6		6
			TEL		

6 Frequently Use Functions

6.1 Device registration

The register code is 16 numbers and letters. For example: GINTEC G20M034804060, A7EC-AC8B-B904-94F5

G20M034804060 is serial number

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A7EC-AC8B-B904-94F5 is register code, when you register, there are two ways: via WEB UI or via Controller. Detailed steps are as follow:

(1) Register via WEB UI

After connecting the Wi-Fi, input IP "192.168.10.1" into your web browser. Then you can see page as show in Figure 6-1. Click "Command", you can find "Register Code". Input your registration code, then click "Register". The receiver will be registered.

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	IZ30486867007923 [Advance UI] English	•
Simple UI	Command	
Status		
Command	System	
Mode Config		
Others Config	Reboot Shutaown	
File		
Firmware	Config and Data	
	Reset Config Clean Storage Register Code	
	sn=Z30486867007923 date=2021-02-22	

Figure 6-1

(2) Register via Controller

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Connect G20M with controller (via Wi-Fi or Bluetooth). Find SurPad software in controller interface, then click "SurPad", it shows as Figure 6-2. Click "Device" you can see "Device Register", click it, then you can see the page to input the code as Figure 6-3. After input the code, click "Registration", then finish the registration.

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6.2 Upgrade firmware

You can upgrade firmware in WEB UI function. In "Firmware", you can find "Upgrade". Click it to select new version of firmware. After select the right version, click"Upload file" to finish upgrade.

Simple UI	Firmware				
	Version				
	System	1.15.2012.19			
	Linux Version	3.18.44 Tue Dec 1 11:50:	17 CST 2020		
	GNSS Firmware	R3.00Build21759			
Firmware	IM19 Firmware	B1.2_A2.9_b9f4f9a11bc9	da		
	Firmware	1.57.2012.301			
			Upgrade		
	TC	Figure 6-4	GIN	EC	ااحا

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6.3 Restore factory settings

In WEB UI, "Command" you can find "Reset Config" under "Config and Data", Click "Reset Config" to reset the device.

		IZ30486867007923 [Adva	nce UI] 🛛 🖡	English	•	
	Simple UI	Command				
	Status					
	Command	System				
	Mode Config					
	Others Config	Reboot				
	File					
	Firmware	Config and Data				
		Reset Config Clean Storage				GIN I
		Register Code				
		Register				
TEL		sn=Z30486867007923 date=2021-02-22				

Figure 6-5

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7 Technical Parameters

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		Channel	432	
GINT	GNSS	Satellites	GPS: L1,L2,L5 GLONASS: L1,L2 BDS: B1,B2,B3 Galileo: E1,E5A,E5B QZSS: L1,L2,L5 SBAS: L1	
		Cold start	<40s	Ter
		Signal recapture	<1s	VIEL
	GINITE	Static Accuracy	Horizontal: \pm (2.5+1×10-6D)mm Vertical: \pm (5.0+1×10-6D)mm	
		DGPS Accuracy	Horizontal: 0.4m; Vertical: 0.8m	
		RTK Accuracy	Horizontal: \pm (10+1×10-6D)mm Vertical: \pm (15+1×10-6D)mm	
	Accuracy	Time Accuracy	20ns	GIV
NTEC	Б	Tilt Measurement Accuracy(within 30°)	<2cm	
		Update Frequency	5Hz	'cc
	DOWED	Battery	Built-in Battery,9600mAh 3.7V	EL
6	POWER	Duration	≥9h	
		Input	5V/2A DC	
		Operation System	Linux	CINITS
		Memory	32G Internal	
		Bluetooth	V2.1+EDR / V4.0 Dual Mode	
TFC		WIFI	802.11 a/b/g/n/ac	
	SYSTEM	4G Network	LTE FDD: B1/B3/B5/B8 LTE TDD: B38/B39/B40/B41 TD-SCDMA: B34/B39	- 1
		GIN	WCDMA: B1/B8 GSM: 900/1800MHz	
GIN	IEL	Tilt Survey	Support Integrated with new calibration free tilt module	
				SINTE

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	INTERFACE	Туре-С	Charge and Data Transmission	
		Other	Micro SIM Slot	F
		Button	Power Button	
GINT	Operation	Indicator	4 indicators: Satellites, Datalink, Bluetooth, Power	
		Material	Magnesium alloy main body, ABS/PC top cover	
	Physical	Dimension	100mm*100mm*61.5mm	TET
		Weight	555g	
	GINITE	Work Temperature	$-20^{\circ}\mathrm{C} \sim +60^{\circ}\mathrm{C}$	
		Stock Temperature	-40°C \sim +80°C	
	ENVIRONMENT Waterproof/ Dustproof		IP65 Standard	
		Shock and	Withstand 1.5m pole drop onto the cement	
		Vibration	ground D	
TCC		Humidity	100%	
NICL				

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